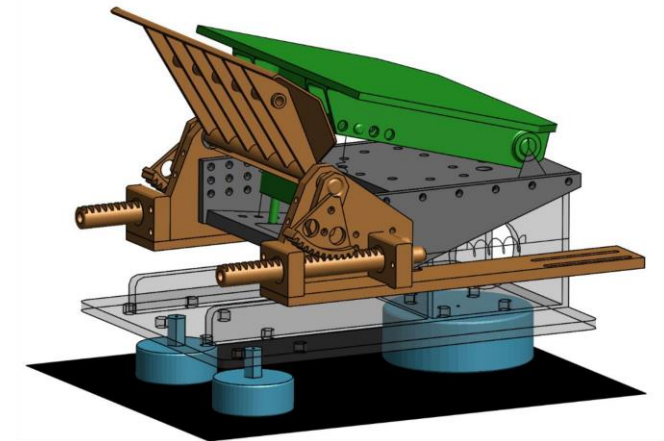


# Update semi rigid seat

**OSCCAR: Update semi rigid seat**



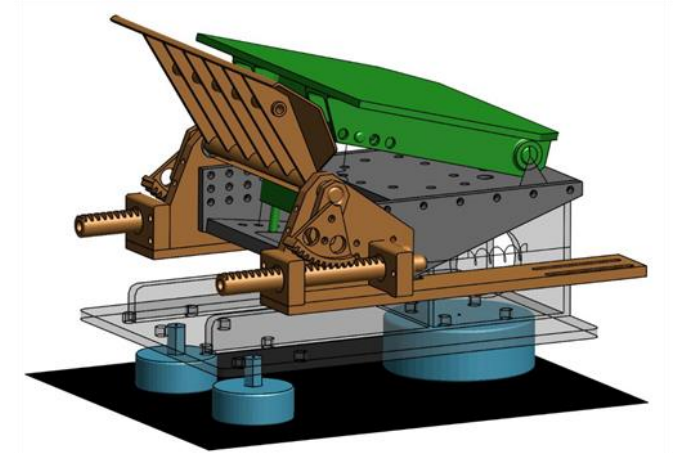
Engineering System International GmbH

2021-09-16

# Overview

## Modifications with respect to WV model

- Topology
  - Added load cell and new floor parts, old base plate removed
  - Seat pan shortened from 300 to 280 mm
  - Positioned as Dyna model
  - Number of TRSFM-Cards reduced from 5 to 3
- Usability
  - Changed initial seat and sub pan angle parameters to be in absolute angles
  - Added sensor cards for the activation/deactivation of the anti-rebound device
- Robustness improvements for VPS working model
  - ACC3D for y-, z-displacement as well as x-, y-, z-rotations replaced by BOUNC\_011111 to avoid precision issues



# Modification

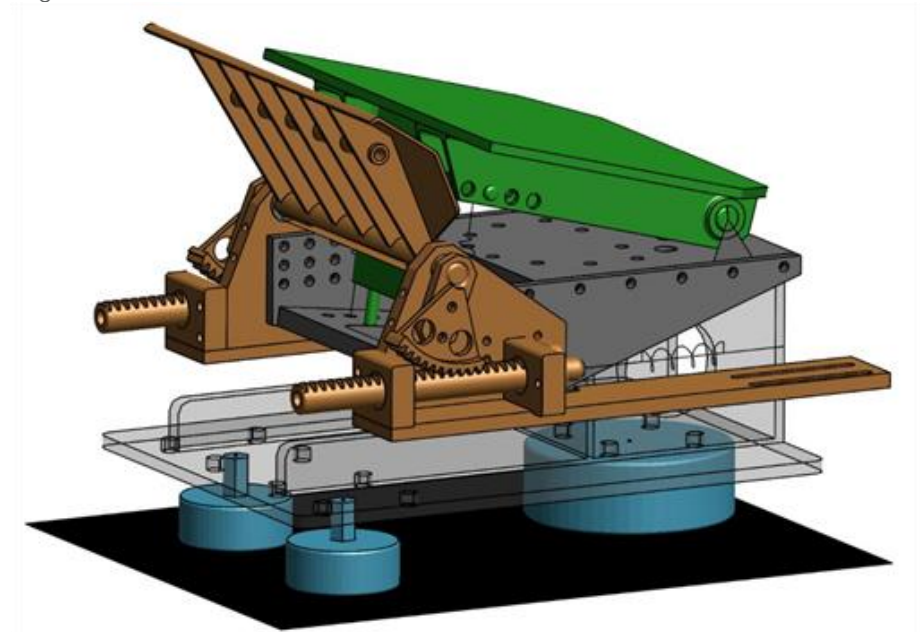
## Activation/Deactivation of anti-rebound device

```

$ Flag to activate/deactivate anti-rebound
$ -----1-----2-----3-----4-----5-----6-----7-----8
PYVAR /          4
NAME Anti-rebound_device_on_off
$ Anti-rebound device (on/off)
$ 0 = off, 1 = on
AntiReb = 1
ar_sen = 10000.0 * AntiReb
END PYVAR
$ -----1-----2-----3-----4
$#          ISENS      ITYP IREVFLG  ISOFST
SENSOR/          4          1
NAME Anti-rebound
$#          TSENS
          <ar_sen>

$
$ -----1-----2-----3-----4
$#          IDDELEM    ISENS  ICRIad
DELEM /          4          4
NAME Anti-rebound
          PART      50162      50164
          END
$ -----1-----2-----3-----4-----5-----6-----7-----8

```



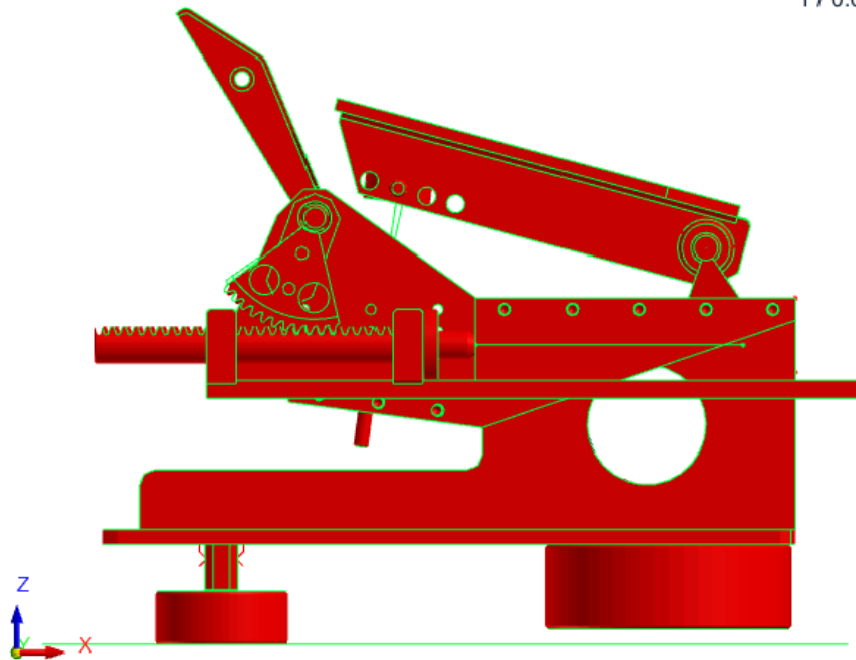
# Semi rigid seat: front position

Results comparison animation state Dyna vs VPS at 0ms

 Dyna  
 VPS

had03\_semi\_rigid\_seat\_37\_front\_conf

1 / 0.000000

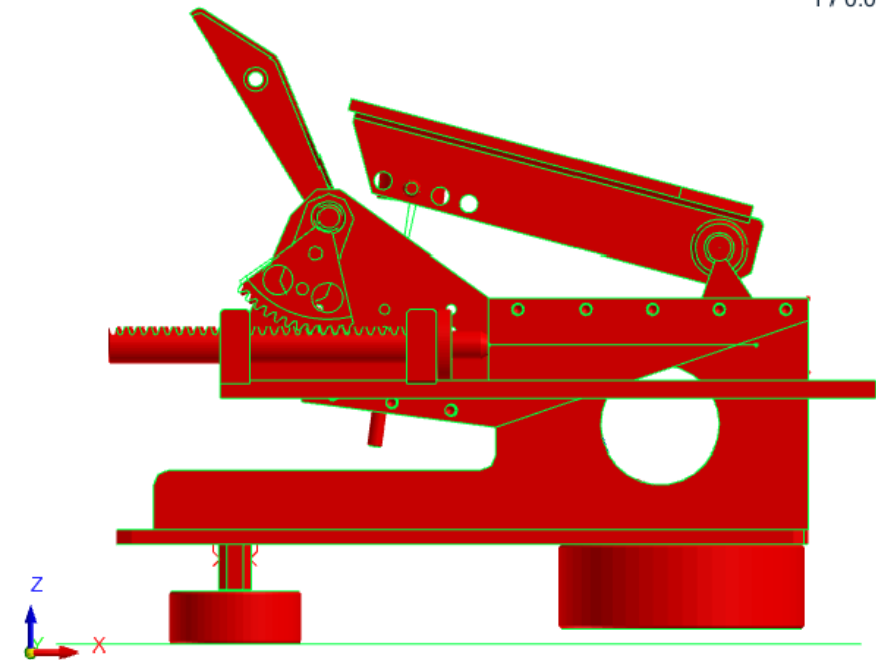


L1:ON\d3plot(A) L2:ON\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: ON**

had03\_semi\_rigid\_seat\_37\_front\_conf

1 / 0.000000



L3:OFF\d3plot(A) L4:OFF\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: OFF**

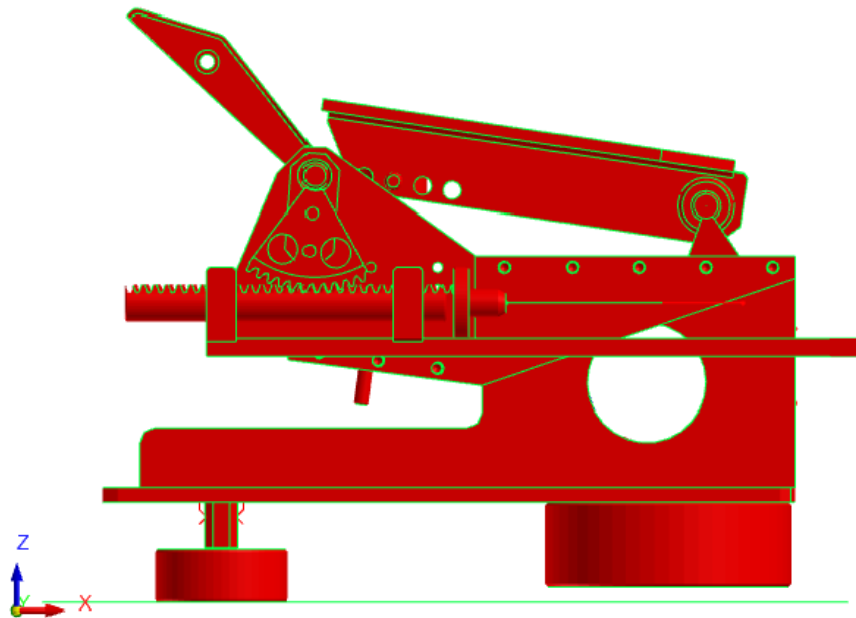
# Semi rigid seat: front position

Results comparison animation state Dyna vs VPS at 100ms

— Dyna  
— VPS

had03\_semi\_rigid\_seat\_37\_front\_conf

76 / 100.000595

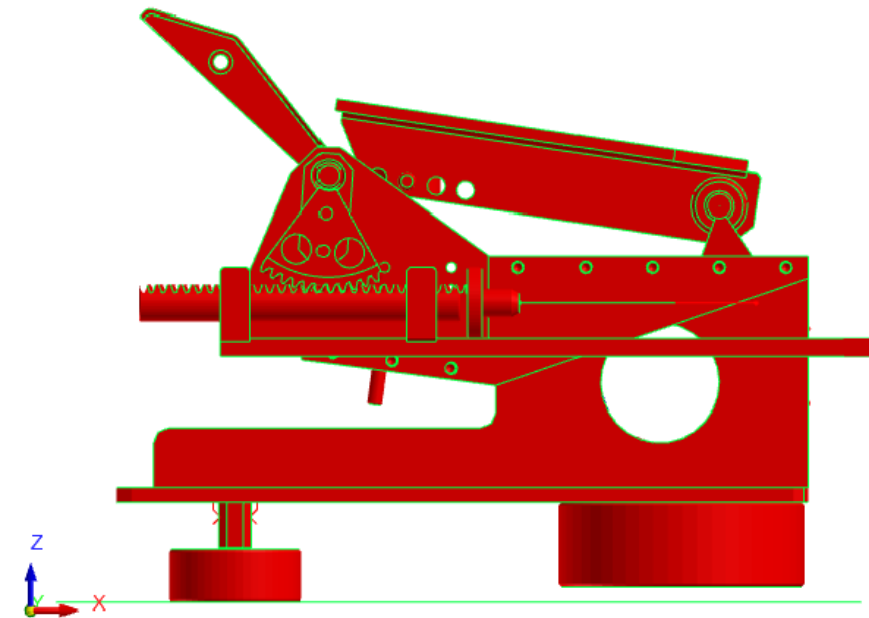


L1:ON\d3plot(A) L2:ON\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: ON**

had03\_semi\_rigid\_seat\_37\_front\_conf

76 / 100.000595



L3:OFF\d3plot(A) L4:OFF\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: OFF**

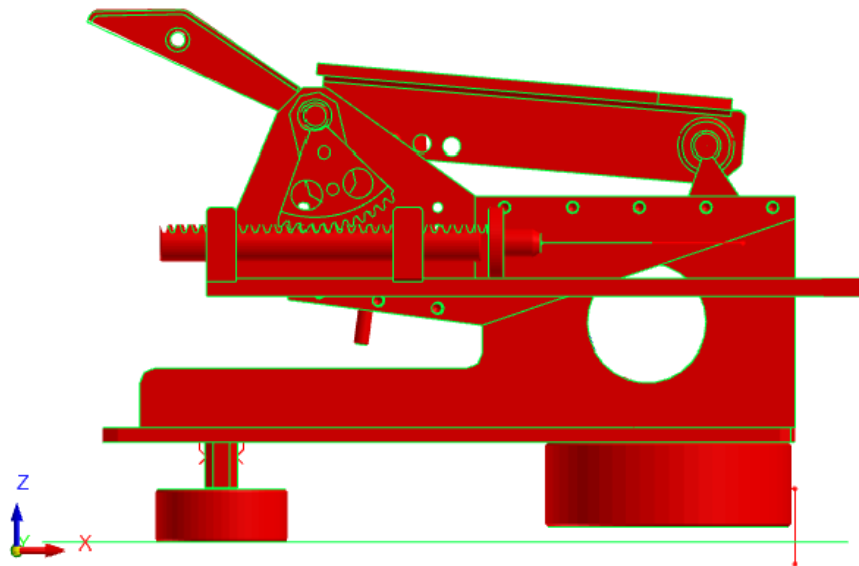
# Semi rigid seat: front position

Results comparison animation state Dyna vs VPS at 200ms

— Dyna  
— VPS

had03\_semi\_rigid\_seat\_37\_front\_conf

151 / 200.000488

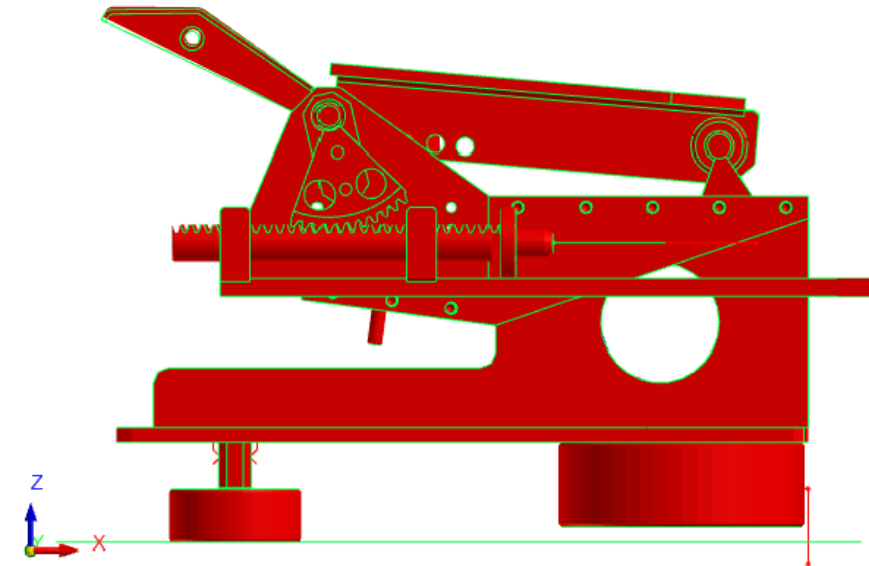


L1:ON\d3plot(A) L2:ON\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: ON**

had03\_semi\_rigid\_seat\_37\_front\_conf

151 / 200.000488



L3:OFF\d3plot(A) L4:OFF\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: OFF**

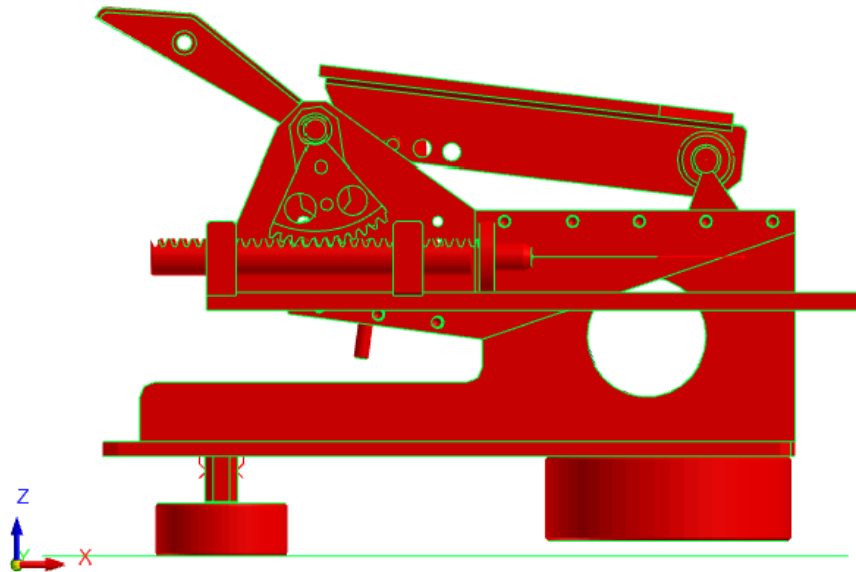
# Semi rigid seat: front position

Results comparison animation state Dyna vs VPS at 300ms

— Dyna  
— VPS

had03\_semi\_rigid\_seat\_37\_front\_conf

226 / 300.000397

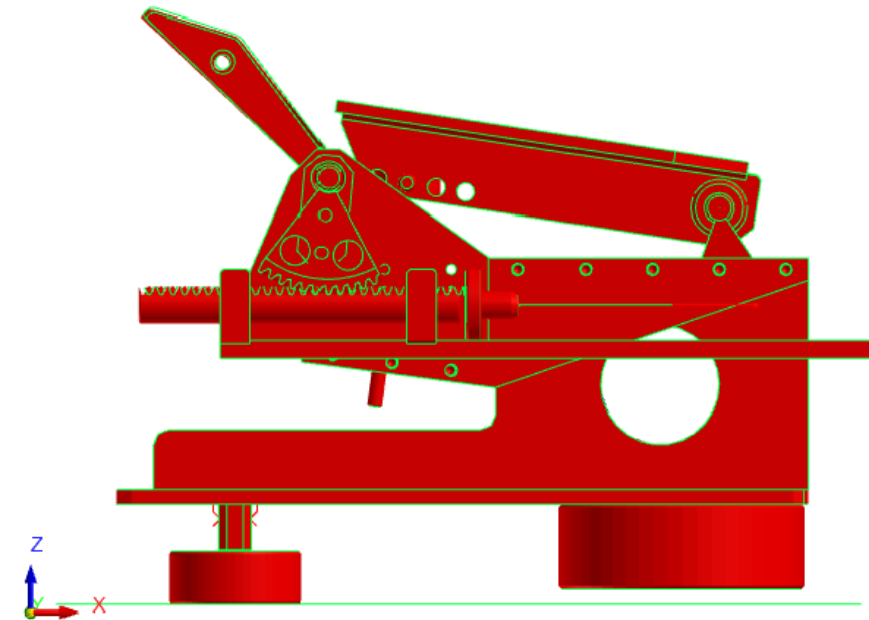


L1:ON\ld3plot(A) L2:ON\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: ON**

had03\_semi\_rigid\_seat\_37\_front\_conf

226 / 300.000397



L3:OFF\ld3plot(A) L4:OFF\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: OFF**

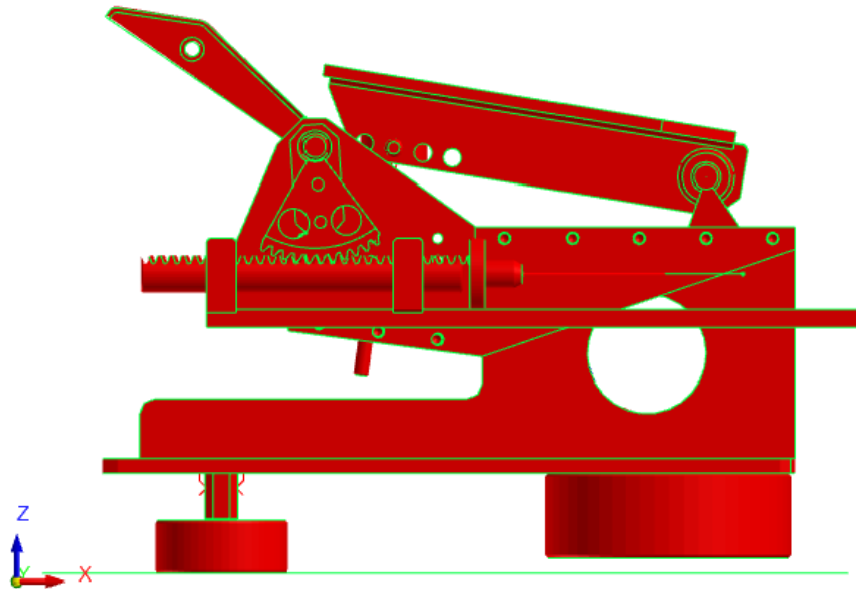
# Semi rigid seat: front position

Results comparison animation state Dyna vs VPS at 400ms

 Dyna  
 VPS

had03\_semi\_rigid\_seat\_37\_front\_conf

302 / 400.000275

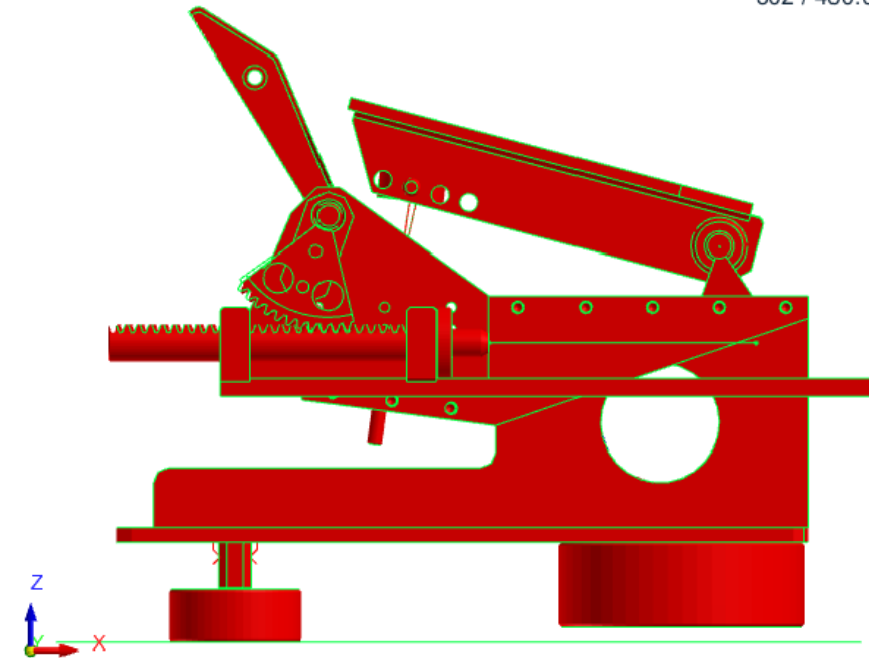


L1:ON\d3plot(A) L2:ON\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: ON**

had03\_semi\_rigid\_seat\_37\_front\_conf

302 / 400.000275



L3:OFF\d3plot(A) L4:OFF\Ramp\_test\_02\_RESULT.erfh5(A)

**Antirebound: OFF**

# Conclusions

The semi rigid seat has been successfully updated according to the new setup.

Comparison between VPS and Dyna show a good agreement for the following scenarios

- 1- Semi rigid seat in front configuration with anti-rebound
- 2- Semi rigid seat in front configuration without anti-rebound